

IEC 60870-5-104 Interoperabilität

1 Interoperability

This companion standard presents sets of parameters and alternatives from which subsets have to be selected to implement particular telecontrol systems. Certain parameter values, such as the number of octets in the COMMON ADDRESS of ASDUs represent mutually exclusive alternatives. This means that only one value of the defined parameters is admitted per system. Other parameters, such as the listed set of different process information in command and in monitor direction allow the specification of the complete set or subsets, as appropriate for given applications. This Clause summarizes the parameters of the previous Clauses to facilitate a suitable selection for a specific application. If a system is composed of equipment stemming from different manufacturers, it is necessary that all partners agree on the selected parameters.

The selected parameters should be marked in the white boxes as follows:

- Function or ASDU is not used
- Function or ASDU is used as standardized (default)
- R Function or ASDU is used in reverse mode
- B Function or ASDU is used in standard and reverse mode

The possible selection (blank, X, R, or B) is specified for each specific Clause or parameter.

NOTE In addition, the full specification of a system may require individual selection of certain parameters for certain Parts of the system, such as the individual selection of scaling factors for individually addressable measured values.

1.1 System or device

(System-specific parameter, indicate the definition of a system or a device by marking one of the following with an "X")

- System Definition
- Controlling station definition (master)
- Controlled station definition (slave)

1.2 Network configuration

(Network-specific parameter, all configurations that are used are to be marked with an "X")

- Point to point
- Multipoint party line
- Multiple point to point
- Multipoint star

1.3 Physical layer

(Network-specific parameter, all interfaces and data rates that are used are to be marked with an "X")

2.3.1 Transmission speed (control direction)

Unbalanced interchange V.24/V.28 Standard	Unbalanced interchange V.24/V.28 Recommended if > 1200	Balanced interchange X.24/X.27
<input type="checkbox"/> 100 bit/s	<input type="checkbox"/> 2400 bit/s	<input type="checkbox"/> 2400 bit/s
<input type="checkbox"/> 200 bit/s	<input type="checkbox"/> 4800 bit/s	<input type="checkbox"/> 4800 bit/s
<input type="checkbox"/> 300 bit/s	<input type="checkbox"/> 9600 bit/s	<input type="checkbox"/> 9600 bit/s
<input type="checkbox"/> 600 bit/s		<input type="checkbox"/> 19200 bit/s
<input type="checkbox"/> 1200 bit/s		<input type="checkbox"/> 38400 bit/s
		<input type="checkbox"/> 56000 bit/s
		<input type="checkbox"/> 64000 bit/s

2.3.2 Transmission speed (monitor direction)

Unbalanced interchange V.24/V.28 Standard	Unbalanced interchange V.24/V.28 Recommended if > 1200	Balanced interchange X.24/X.27
<input type="checkbox"/> 100 bit/s	<input type="checkbox"/> 2400 bit/s	<input type="checkbox"/> 2400 bit/s
<input type="checkbox"/> 200 bit/s	<input type="checkbox"/> 4800 bit/s	<input type="checkbox"/> 4800 bit/s
<input type="checkbox"/> 300 bit/s	<input type="checkbox"/> 9600 bit/s	<input type="checkbox"/> 9600 bit/s
<input type="checkbox"/> 600 bit/s		<input type="checkbox"/> 19200 bit/s
<input type="checkbox"/> 1200 bit/s		<input type="checkbox"/> 38400 bit/s
		<input type="checkbox"/> 56000 bit/s
		<input type="checkbox"/> 64000 bit/s

1.4 Link layer

(Network-specific parameter, all options that are used are to be marked "X". Specify the maximum frame length. If a non-standard assignment of class 2 messages is implemented for unbalanced transmission, indicate the Type ID and COT of all messages assigned to class 2.)

~~Frame format FT 1.2, single character 1 and the fixed time out interval are used exclusively in this companion standard.~~

<p>Link transmission procedure</p> <p><input type="checkbox"/> Balanced transmission</p> <p><input type="checkbox"/> Unbalanced transmission</p> <p>Frame Length</p> <p><input type="checkbox"/> <u>Minimum length L</u></p>	<p>Address field of the link</p> <p><input type="checkbox"/> Not Present (balanced transmission only)</p> <p><input type="checkbox"/> One octet</p> <p><input type="checkbox"/> Two octets</p> <p><input type="checkbox"/> Structured</p> <p><input type="checkbox"/> Unstructured</p>
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When using an unbalanced link layer, the following ASDU types are returned in class 2 Messages (low priority) with the indicated causes of transmission:

~~The standard assignment of ASDUs to class 2 messages is used as follows:~~

Type identification	Cause of Transmission
9, 11, 13	<1>

~~A special assignment of ASDUs to class 2 messages is used as follows:~~

Type identification	Cause of Transmission

~~NOTE In response to a class 2 poll, a controlled station may respond with class 1 data when there is no class 2 data available.~~

1.5 Application layer

Transmission mode for application data

Mode 1 (least significant octet first), as defined in 4.10 of IEC 60870-5-4, is used exclusively in this companion standard.

2.5.1 Common address of ASDU

(System-specific parameter, all configurations that are used are to be marked with an "X")

One octet Two Octets

2.5.2 Information object address

(System-specific parameter, all configurations that are used are to be marked with an "X")

One octet Structured
 Two octets Unstructured
 Three octets

2.5.3 Cause of transmission

(System-specific parameter, all configurations that are used are to be marked with an "X")

One octet Two Octets (with originator address)
Originator address is set to 0 if not used

2.5.4 Length of APDU

(System-specific parameter, specify the maximum length of the APDU per system)

The maximum length of the APDU is 253 (default). The maximum length may be reduced by the system.

253 Maximum length of APDU per system

2.5.5 Selection of standard ASDUs

2.5.5.1 Process information in monitor direction

(Station-specific parameter, mark each type ID with an “X” if it is only used in the standard direction, “R” if only used in the reverse direction, and “B” if used in both directions)

<input checked="" type="checkbox"/>	<1> := Single-point information	M_SP_NA_1
<input type="checkbox"/>	<2> := Single-point information with CP24Time	M_SP_TA_1
<input checked="" type="checkbox"/>	<3> := Double-point information	M_DP_NA_1
<input type="checkbox"/>	<4> := Double-point information with CP24Time	M_DP_TA_1
<input checked="" type="checkbox"/>	<5> := Step position information	M_ST_NA_1
<input type="checkbox"/>	<6> := Step position information with CP24Time	M_ST_TA_1
<input checked="" type="checkbox"/>	<7> := Bitstring of 32 bit	M_BO_NA_1
<input type="checkbox"/>	<8> := Bitstring of 32 bit with CP24Time	M_BO_TA_1
<input checked="" type="checkbox"/>	<9> := Measured value, normalized value	M_ME_NA_1
<input type="checkbox"/>	<10> := Measured value, normalized value with CP24Time	M_ME_TA_1
<input checked="" type="checkbox"/>	<11> := Measured value, scaled value	M_ME_NB_1
<input type="checkbox"/>	<12> := Measured value, scaled value with CP24Time	M_ME_TB_1
<input checked="" type="checkbox"/>	<13> := Measured value, short floating point value	M_ME_NC_1
<input type="checkbox"/>	<14> := Measured value, short floating point value with CP24Time	M_ME_TC_1
<input checked="" type="checkbox"/>	<15> := Integrated totals	M_IT_NA_1
<input type="checkbox"/>	<16> := Integrated totals with CP24Time	M_IT_TA_1
<input type="checkbox"/>	<17> := Event of protection equipment with CP24Time	M_EP_TA_1
<input type="checkbox"/>	<18> := Packed start events of protection equipment with CP24Time	M_EP_TB_1
<input type="checkbox"/>	<19> := Packed output circuit information of protection with CP24Time	M_EP_TC_1
<input type="checkbox"/>	<20> := Packed single-point information with status change detection	M_PS_NA_1
<input type="checkbox"/>	<21> := Measured value, normalized value without quality descriptor	M_ME_ND_1
<input checked="" type="checkbox"/>	<30> := Single-point information with CP56Time	M_SP_TB_1
<input checked="" type="checkbox"/>	<31> := Double-point information with CP56Time	M_DP_TB_1
<input checked="" type="checkbox"/>	<32> := Step position information with CP56Time	M_ST_TB_1
<input checked="" type="checkbox"/>	<33> := Bitstring of 32 bit with CP56Time	M_BO_TB_1
<input checked="" type="checkbox"/>	<34> := Measured value, normalized value with CP56Time	M_ME_TD_1
<input checked="" type="checkbox"/>	<35> := Measured value, scaled value with CP56Time	M_ME_TE_1
<input checked="" type="checkbox"/>	<36> := Measured value, floating point value with CP56Time	M_ME_TF_1
<input checked="" type="checkbox"/>	<37> := Integrated totals with CP56Time	M_IT_TB_1
<input type="checkbox"/>	<38> := Event of protection equipment with CP56Time	M_EP_TD_1
<input type="checkbox"/>	<39> := Packed start events of protection with CP56Time	M_EP_TE_1
<input type="checkbox"/>	<40> := Packed output circuit information of protection with CP56Time	M_EP_TF_1

Either ASDUs of the set <2>, <4>, <6>, <8>, <10>, <12>, <14>, <16>, <17>, <18>, <19> or of the set <30–40> are used.

2.5.5.2 Process information in control direction

(Station-specific parameter, mark each type ID with an “X” if it is only used in the standard direction, “R” if only used in the reverse direction, and “B” if used in both directions)

<input checked="" type="checkbox"/> <45> := Single command	C_SC_NA_1
<input checked="" type="checkbox"/> <46> := Double command	C_DC_NA_1
<input checked="" type="checkbox"/> <47> := Regulating step command	C_RC_NA_1
<input checked="" type="checkbox"/> <48> := Set point command, normalized value	C_SE_NA_1
<input checked="" type="checkbox"/> <49> := Set point command, scaled value	C_SE_NB_1
<input checked="" type="checkbox"/> <50> := Set point command, short floating point value	C_SE_NC_1
<input checked="" type="checkbox"/> <51> := Bitstring of 32 bit	C_BO_NA_1
<input checked="" type="checkbox"/> <58> := Single command with CP56Time	C_SC_TA_1
<input checked="" type="checkbox"/> <59> := Double command with CP56Time	C_DC_TA_1
<input checked="" type="checkbox"/> <60> := Regulating step command with CP56Time	C_RC_TA_1
<input checked="" type="checkbox"/> <61> := Set point command, normalized value with CP56Time	C_SE_TA_1
<input checked="" type="checkbox"/> <62> := Set point command, scaled value with CP56Time	C_SE_TB_1
<input checked="" type="checkbox"/> <63> := Set point command, short floating point value with CP56Time	C_SE_TC_1
<input checked="" type="checkbox"/> <64> := Bitstring of 32 bit command with CP56Time	C_BO_TA_1

Either the ASDUs of the set <45> – <51> or of the set <58> – <64> are used.

2.5.5.3 System information in monitor direction

(Station-specific parameter, mark with an “X” if it is only used in the standard direction, “R” if only used in the reverse direction, and “B” if used in both directions)

<input checked="" type="checkbox"/> <70> := End of initialisation	M_EI_NA_1
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2.5.5.4 System information in control direction

(Station-specific parameter, mark with an “X” if it is only used in the standard direction, “R” if only used in the reverse direction, and “B” if used in both directions, “S” if it is only used in servers in the standard direction)

<input checked="" type="checkbox"/> <100> := Interrogation command	C_IC_NA_1
<input checked="" type="checkbox"/> <101> := Counter interrogation command	C_CI_NA_1
<input checked="" type="checkbox"/> <102> := Read command	C_RD_NA_1
<input checked="" type="checkbox"/> <103> := Clock synchronization command	C_CS_NA_1
<input type="checkbox"/> <104> := Test command	C_TS_NA_1
<input checked="" type="checkbox"/> <105> := Reset process command	C_RP_NA_1
<input checked="" type="checkbox"/> <106> := Delay acquisition command	C_CD_NA_1
<input type="checkbox"/> <107> := Test command with CP56Time	C_TS_TA_1

2.5.5.5 Parameter in control direction

(Station-specific parameter, mark each type ID with an “X” if it is only used in the standard direction, “R” if only used in the reverse direction, and “B” if used in both directions)

<input checked="" type="checkbox"/> <110> := Parameter of measured value, normalized value	P_ME_NA_1
<input checked="" type="checkbox"/> <111> := Parameter of measured value, scaled value	P_ME_NB_1
<input checked="" type="checkbox"/> <112> := Parameter of measured value, short floating point value	P_ME_NC_1
<input checked="" type="checkbox"/> <113> := Parameter activation	P_AC_NA_1

2.5.6 File transfer

(Station-specific parameter, mark each type ID with an “X” if it is only used in the standard direction, “R” if only used in the reverse direction, and “B” if used in both directions)

<input checked="" type="checkbox"/> <120> := File ready	F_FR_NA_1
<input checked="" type="checkbox"/> <121> := Section ready	F_SR_NA_1
<input checked="" type="checkbox"/> <122> := Call directory, select file, call file, call section	F_SC_NA_1
<input checked="" type="checkbox"/> <123> := Last section, last segment	F_LS_NA_1
<input checked="" type="checkbox"/> <124> := Ack file, ack section	F_AF_NA_1
<input checked="" type="checkbox"/> <125> := Segment	F_SG_NA_1
<input checked="" type="checkbox"/> <126> := Directory {blank or X, only available in monitor direction}	F_DR_TA_1
<input type="checkbox"/> <127> := Query Log – Request Archive file	F_SC_NB_1

2.5.7 Type identification and cause of transmission assignments

(Station-specific parameters)

Shaded boxes are not required.

Blank = function or ASDU is not used.

Mark type identification/cause of transmission combinations:

“X” if used only in the standard direction;

“R” if used only in the reverse direction;

“B” if used in both directions.

“S” if used only in the server side in the standard direction;

“opt” optional

1.6 Basic application functions

2.6.1 Station initialization

(Station-specific parameter, mark with an “X” if function is used)

Remote initialization

2.6.2 Cyclic data transmission

(Station-specific parameter, mark with an “X” if function is used only in the standard direction, “R” if used only in the reverse direction, and “B” if used in both directions)

Cyclic data Transmission

2.6.3 Read Procedure

(Station-specific parameter, mark with an “X” if function is used only in the standard direction, “R” if used only in the reverse direction, and “B” if used in both directions)

Read procedure

2.6.4 Spontaneous transmission

(Station-specific parameter, mark with an “X” if function is used only in the standard direction, “R” if used only in the reverse direction, and “B” if used in both directions)

Spontaneous transmission

2.6.5 Double transmission of information objects with cause of transmission spontaneous (Station-specific parameter, mark each information type with an “X” where both a type ID without time and corresponding type ID with time are issued in response to a single spontaneous change of a monitored object)

The following type identifications may be transmitted in succession caused by a single status change of an information object. The particular information object addresses for which double transmission is enabled are defined in a project-specific list.

Single-point information M_SP_NA_1, M_SP_TA_1, M_SP_TB_1 and M_PS_NA_1

Double-point information M_DP_NA1, M_DP_TA_1 and M_DP_TB_1

Step position information M_ST_NA_1, M_ST_TA_1 and M_ST_TB_1

Bitstring of 32 bit M_BO_NA_1, M_BO_TA_1 and M_BO_TB_1

Measured value, normalized value M_ME_NA_1, M_ME_TA_1 and M_ME_TD_1

Measured value, scaled value M_ME_NB_1, M_ME_TB_1 and M_ME_TE_1

Measured value, floating point number M_ME_NC_1, M_ME_TC_1 and M_ME_TF_1

2.6.6 Station interrogation

(Station-specific parameter, mark with an “X” if function is used only in the standard direction, “R” if used only in the reverse direction, and “B” if used in both directions)

<input checked="" type="checkbox"/> global		
<input checked="" type="checkbox"/> group 01	<input checked="" type="checkbox"/> group 07	<input checked="" type="checkbox"/> group 13
<input checked="" type="checkbox"/> group 02	<input checked="" type="checkbox"/> group 08	<input checked="" type="checkbox"/> group 14
<input checked="" type="checkbox"/> group 03	<input checked="" type="checkbox"/> group 09	<input checked="" type="checkbox"/> group 15
<input checked="" type="checkbox"/> group 04	<input checked="" type="checkbox"/> group 10	<input checked="" type="checkbox"/> group 16
<input checked="" type="checkbox"/> group 05	<input checked="" type="checkbox"/> group 11	
<input checked="" type="checkbox"/> group 06	<input checked="" type="checkbox"/> group 12	

2.6.7 Clock synchronization

(Station-specific parameter, mark with an “X” if function is used only in the standard direction, “R” if used only in the reverse direction, and “B” if used in both directions)

<input checked="" type="checkbox"/> Clock synchronization
<input type="checkbox"/> opt Day of week used
<input type="checkbox"/> opt RES1, GEN (time tag substituted/ not substituted) used SU-
<input type="checkbox"/> opt bit (summertime) used

2.6.8 Command transmission

(Object-specific parameter, mark with an “X” if function is used only in the standard direction, “R” if used only in the reverse direction, and “B” if used in both directions)

<input checked="" type="checkbox"/> Direct command transmission
<input checked="" type="checkbox"/> Direct set point command transmission
<input checked="" type="checkbox"/> Select and execute command
<input checked="" type="checkbox"/> Select and execute set point command
<input type="checkbox"/> opt C_SE ACTTERM used
<input checked="" type="checkbox"/> No additional definition
<input checked="" type="checkbox"/> Short-pulse duration (duration by a system parameter in the controlled station)
<input checked="" type="checkbox"/> Long-pulse duration (duration by a system parameter in the controlled station)
<input checked="" type="checkbox"/> Persistent output
<input checked="" type="checkbox"/> Supervision of maximum delay of command in command direction
<input type="checkbox"/> Maximum allowable delay of commands and set point commands

2.6.9 Transmission of integrated totals

(Station- or object-specific parameter, mark with an "X" if function is used only in the standard direction, "R" if used only in the reverse direction, and "B" if used in both directions)

- Mode A: local freeze with spontaneous transmission
- Mode B: local freeze with counter interrogation
- Mode C: freeze and transmit by counter interrogation commands
- Mode D: freeze by counter-interrogation command, frozen values reported spontaneously
- Counter read
- Counter freeze without reset
- Counter freeze with reset
- Counter reset
- General request counter
- Request counter group 1
- Request counter group 2
- Request counter group 3
- Request counter group 4

2.6.10 Parameter loading

(Object-specific parameter, mark with an "X" if function is used only in the standard direction, "R" if used only in the reverse direction, and "B" if used in both directions)

- opt Threshold value
- opt Smoothing factor
- opt Low limit for transmission of measured value
- opt High limit for transmission of measured value

2.6.11 Parameter activation

(Object-specific parameter, mark with an "X" if function is used only in the standard direction, "R" if used only in the reverse direction, and "B" if used in both directions)

- opt Act/deact of persistent cyclic or periodic transmission of the addressed object

2.6.12 Test procedure

(Station-specific parameter, mark with an "X" if function is used only in the standard direction, "R" if used only in the reverse direction, and "B" if used in both directions)

- Test procedure

2.6.13 File transfer in monitor direction

- Transparent file
- Transmission of disturbance data of protection equipment
- Transmission of sequences of events
- Transmission of sequences of recorded analogue values

2.6.14 File transfer in control direction

- Transparent file

2.6.15 Background scan

(Station-specific parameter, mark with an “X” if function is used only in the standard direction, “R” if used only in the reverse direction, and “B” if used in both directions)

- Background scan Direct

2.6.16 Acquisition of transmission delay

(Station-specific parameter, mark with an “X” if function is used only in the standard direction, “R” if used only in the reverse direction, and “B” if used in both directions)

- Acquisition of transmission delay

2.6.17 Definition of time-outs

Par.	Default	Remarks
t0	30 s	Time-out of connection establishment
t1	15 s	Time-out of send or test APDUs
t2	10 s	Time-out for acknowledges in case of no data messages $t2 < t1$
t3	20 s	Time-out for sending test frames in case of a long idle state

Maximum range of values for all time-outs: 1 to 255 s, accuracy 1 s.

2.6.18 Maximum number of outstanding I format APDUs k and latest acknowledge APDUs (w)

Par.	Default	Remarks
k	12	Maximum difference receive sequence number to send state
w	8	Maximum difference receive sequence number to send state

Maximum range of values k: 1 to 32 APDUs, accuracy 1 APDU

Maximum range of values w: 1 to 32 APDUs, accuracy 1 APDU

(Recommendation: w should not exceed two-thirds of k).

2.6.19 Portnumber

Par.	Default	Remarks	
Portnumber	2404	Configurable	

2.6.20 Redundant connections

4 Number N of redundancy group connections used

2.6.21 RFC 2200 suite

RFC 2200 is an official Internet Standard which describes the state of standardization of protocols used in the Internet as determined by the Internet Architecture Board (IAB). It offers a broad spectrum of actual standards used in the Internet. The suitable selection of documents from RFC 2200 defined in this standard for given projects has to be chosen by the user of this standard.

Ethernet 802.3

Serial X.21 interface

Other selection from RFC